

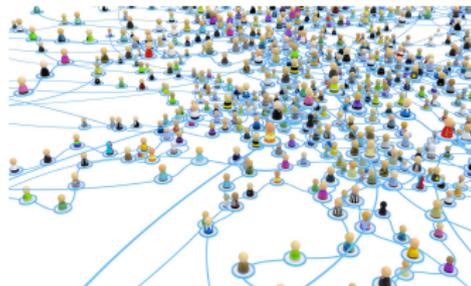
Graphon games: A statistical framework for network games and interventions

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Motivation



Social interactions

- Adoption of innovations, behaviors
- Opinion formation
- Social learning



Economic interactions

- Public good provision
- Competition among firms
- Financial trades

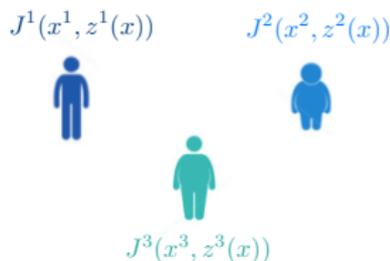
In many social and economic settings, decisions of individuals are affected more by the actions of their **friends, colleagues, peers and competitors**.

Network game model

Consider a network game defined by:

- N agents
- interacting over a network $G \in \mathbb{R}^{N \times N}$

$$\begin{cases} G_{ij} \geq 0 & \text{influence of } j \text{ on } i \\ G_{ii} = 0 & \text{no self loops} \end{cases}$$



Each agent i aims at minimizing its cost function

- strategy: $x^i \in \mathbb{R}^n$
- cost: $J^i(x^i, z^i(x)) : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$
- feasible set: $\mathcal{X}^i \subset \mathbb{R}^n$
- aggregate: $z^i(x) := \frac{1}{N} \sum_{j=1}^N G_{ij} x^j$

Standing assumption

- $\mathcal{X}^i \subset \mathbb{R}^n$ compact and convex;
- $J^i(x^i, z^i(x))$ strongly convex in x^i , for all $x^{-i} \in \mathcal{X}^{-i}$;
- $J^i(x^i, z^i) \in \mathcal{C}^2$ in $[x^i; z^i]$.

Linear quadratic network games

- Each agent chooses an **action** $x^i \geq 0$...
→ how much effort exerted on an activity
(e.g. education, smoking, public goods)
- Agent i **cost function**:

$$J^i(x^i, z^i(x)) = \underbrace{\frac{1}{2}(x^i)^2 - a^i x^i}_{\text{cost isolation}} - \underbrace{K \cdot z^i(x)}_{\text{network effects}} x^i$$

- aggregate: $z^i(x) = \frac{1}{N} \sum_{j \neq i} G_{ij} x^j$
- K determines how much neighbor actions affect agent's payoff.
($K > 0$ strategic complements; $K < 0$ strategic substitutes)

A set of strategies $\{\bar{x}^i\}_{i=1}^N$ is a **Nash equilibrium** if for each player i ,

$$J^i(\bar{x}^i, z^i(\bar{x})) \leq J^i(x^i, z^i(\bar{x})), \text{ for all } x^i \in \mathcal{X}^i.$$

Literature and main question

What is the impact of network structure on equilibrium outcome?

- How does individual **network position** determine individual play?

Ballester et al. (2006); Bramoullé and Kranton (2007); Bramoullé et al. (2014); Belhaj et al. (2014); Jackson and Zenou (2014); Acemoglu et al. (2015); Allouch (2015); Melo (2017); Parise and Ozdaglar (2018)

- How does a central planner **target interventions**?

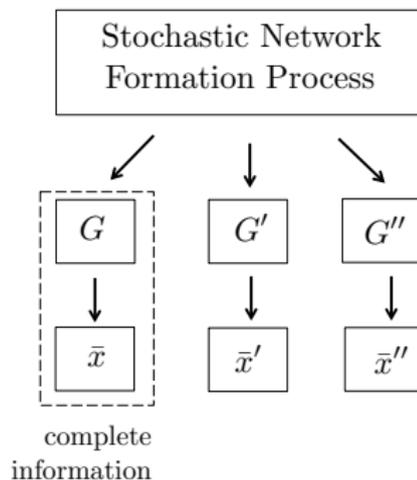
- Ballester et al. (2006): key-player removal in crime applications
- Candogan et al. (2012): optimal pricing for monopolist
- Galeotti et al. (2017): budget allocation in network games

↔ require exact network information

Applications where network is large, changing over time or multiple networks

Can we regulate strategic behavior by using only **statistical information** about network interactions?

A statistical framework for network games



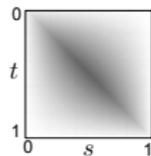
Sampled network game = game over a sampled network

- Related work on distribution of [centrality measures](#):
Dasaratha (2017), Avella-Medina, Parise, Schaub, and Segarra (2018)

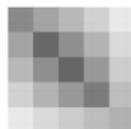
Graphons as stochastic network formation processes

Graphons - [Lovász, 2012]

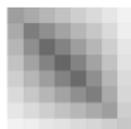
A symmetric measurable function $W : [0, 1]^2 \rightarrow [0, 1]$



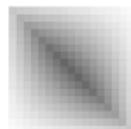
1) Limit of graph: $W(s, t) = \text{interaction } s, t \in [0, 1]$



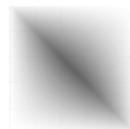
$N = 5$



$N = 10$



$N = 20$

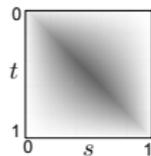


$N = \infty$

Graphons as stochastic network formation processes

Graphons - [Lovász, 2012]

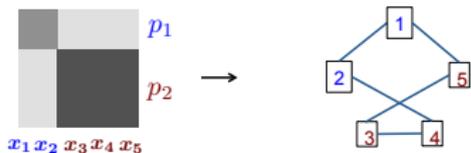
A symmetric measurable function $W : [0, 1]^2 \rightarrow [0, 1]$



2) Random graph model:



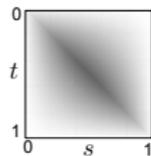
Generalize **parametric models** such as Erdos-Renyi, Stochastic Block model



Graphons as stochastic network formation processes

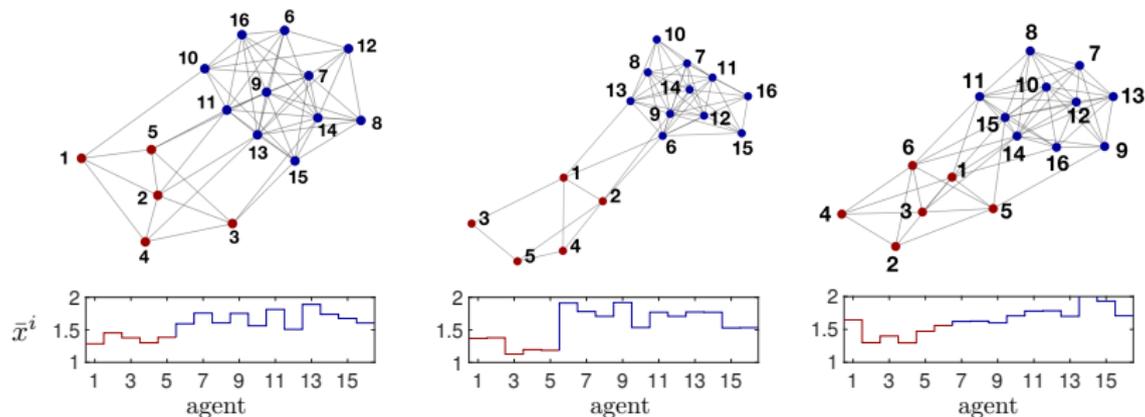
Graphons - [Lovász, 2012]

A symmetric measurable function $W : [0, 1]^2 \rightarrow [0, 1]$



- **Theory:**
[Lovász, Szegedy, 2006], [Lovász, 2012], [Borgs et al., 2008]
- **Applications:**
 - community detection [Eldridge et al., 2016],
 - crowd-sourcing [Lee and Shah, 2017],
 - signal processing [Morency and Leus, 2017],
 - optimal control of dynamical systems [Gao and Caines, 2017]
 - graphon mean field games: [Caines and Huang, 2018]
 - ...
- **Key idea of this work:**
combine network game theory with graphon theory

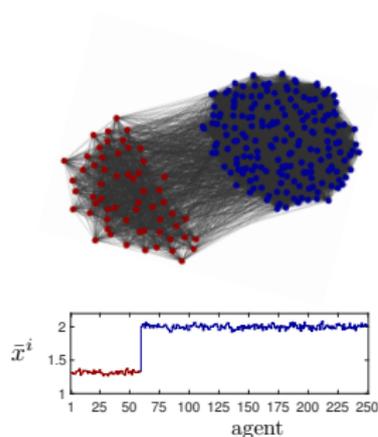
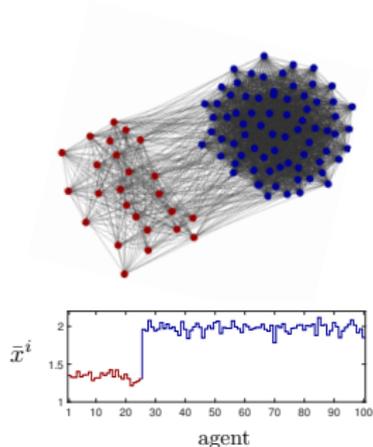
Illustration for a SBM



Questions:

1. How close are Nash equilibria in different sampled network games?

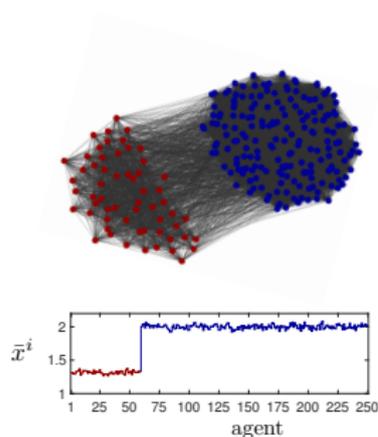
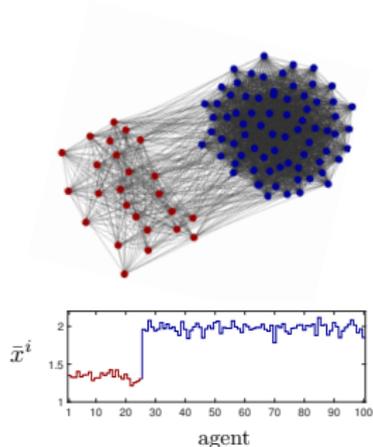
Illustration for a SBM



Questions:

1. How close are Nash equilibria in different sampled network games?
2. Will the Nash equilibria converge to a deterministic profile for N large?

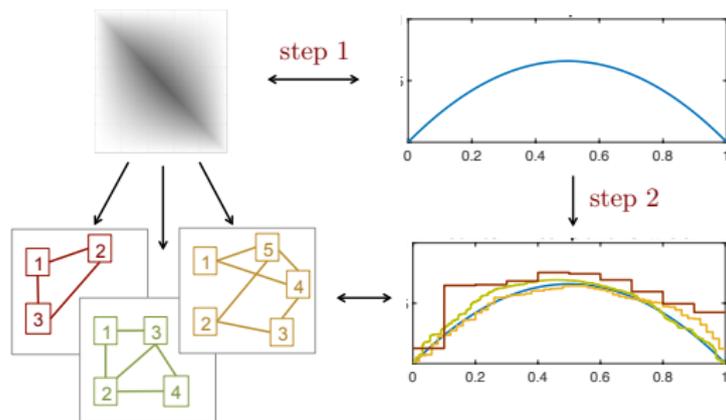
Illustration for a SBM



Questions:

1. How close are Nash equilibria in different sampled network games?
2. Will the Nash equilibria converge to a deterministic profile for N large?
3. Can we exploit this property to design robust interventions for sampled network games?

Talk outline



Step 1 Define graphon games for infinite populations

- define equilibrium
- existence, uniqueness and sensitivity

Step 2 Relate infinite graphon games to sampled network games

- reformulate a network games as a step-function graphon game
- relate equilibria of graphon games & sampled network games (bound the distance in terms on the population size)

Step 3 Design interventions for sampled network games based on graphon model

Step 4 Incomplete information in sampled network games

Step 1:
Infinite population

Network versus graphon games

	Network games	Graphon games
- Agents:	$i \in \{1, \dots, N\}$	$s \in [0, 1]$
- Interactions:	$G \in \mathbb{R}^{N \times N}$	$W : [0, 1]^2 \rightarrow [0, 1]$
- Strategy:	$x^i \in \mathcal{X}^i$	$x(s) \in \mathcal{X}(s)$
- Cost function:	$J(x^i, z^i)$	$J(x(s), z(s x))$
- Aggregate:	$z^i(x) := \frac{1}{N} \sum_{j=1}^N G_{ij} x^j$	$z(s x) := \int_0^1 W(s, t) x(t) dt$

Remarks:

- Agents are a continuum in $[0, 1]$ (non-atomic)
- $W(s, t)$ represents the interaction among the non-atomic agents s and t
- The agents cost function is the same in network and in graphon games
- A **strategy profile is a function** $x : [0, 1] \rightarrow \mathcal{X}$

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Definition: Nash equilibrium

A function $\bar{x}(s) \in \mathcal{X}(s)$ is a Nash equilibrium if for all $s \in [0, 1]$

$$J(\bar{x}(s), z(s | \bar{x})) \leq J(\tilde{x}, z(s | \bar{x})) \text{ for all } \tilde{x} \in \mathcal{X}(s)$$

Similarity with Wardrop equilibrium for non-atomic congestion games

[Wardrop, 1900], [Smith, 1979]

Network versus graphon games

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- Interactions:	$G \in \mathbb{R}^{N \times N}$	$W : [0, 1]^2 \rightarrow [0, 1]$
- Strategy:	$x^i \in \mathcal{X}^i$	$x(s) \in \mathcal{X}(s)$
- Cost function:	$J(x^i, z^i)$	$J(x(s), z(s x))$
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A function $\bar{x}(s) \in \mathcal{X}(s)$ is a Nash equilibrium if for all $s \in [0, 1]$

$$J(\bar{x}(s), z(s | \bar{x})) \leq J(\tilde{x}, z(s | \tilde{x})) \text{ for all } \tilde{x} \in \mathcal{X}(s)$$

Does a Nash equilibrium exist? Is it unique?

The graphon operator

Adjacency matrix

$$G \in \mathbb{R}^{N \times N}$$

$$v \mapsto Gv$$

$$Gv = \lambda v$$

Graphon operator

$$\mathbb{W} : L^2([0, 1]) \mapsto L^2([0, 1])$$

$$f \mapsto (\mathbb{W}f)(s) = \int_0^1 W(s, t)f(t)dt.$$

$$(\mathbb{W}f)(s) = \lambda f(s)$$

Properties of \mathbb{W} - [Lovász, 2012]

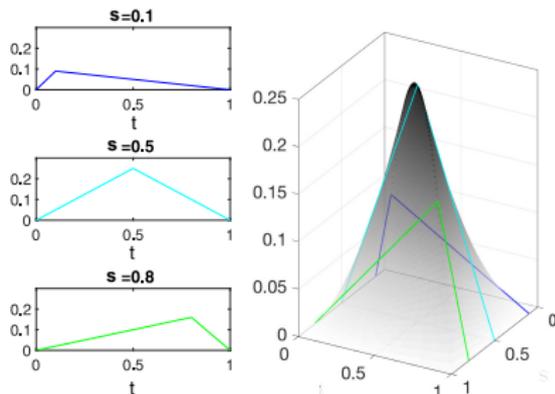
1. \mathbb{W} is a linear, continuous, bounded operator;
2. all the eigenvalues of \mathbb{W} are real;
3. $\|\mathbb{W}\| := \sup_{f \in L^2([0,1]), \|f\|_L=1} \|\mathbb{W}f\|_L = \lambda_{\max}(\mathbb{W})$.

An example

Consider an infinite population of agents which are **spatially located along a line** (e.g. a street).

- $s \in [0, 1]$ = position along line
- influence between agents is a decreasing function of the spatial distance
- central agents are affected more

minmax graphon



$$W(s, t) = \min(s, t)(1 - \max(s, t))$$

Spectral properties:

$$\lambda_h := \frac{1}{\pi^2 h^2}, \quad \psi_h(s) := \sqrt{2} \sin(h\pi s) \quad \forall h \in \{1, 2, \dots, \infty\}$$

W has an **infinite, but countable**, number of nonzero eigenvalues, with an accumulation point at zero. Moreover, $\lambda_{\max}(W) = \frac{1}{\pi^2}$.

Reformulation as fixed point of the best response mapping

Nash equilibrium

$$\bar{x}(s) = \arg \min_{\tilde{x} \in \mathcal{X}(s)} J(\tilde{x}, z(s | \bar{x}))$$

- consider a **fixed strategy profile** $x(s)$
- the corresponding **local aggregate** function is

$$z_x(s) := z(s | x) = \int_0^1 W(s, t)x(t)dt = (\mathbb{W}x)(s)$$

- Define the **best response operator** \mathbb{B}

$$(\mathbb{B}z)(s) := \arg \min_{\tilde{x} \in \mathcal{X}(s)} J(\tilde{x}, z(s)),$$

- the **best response mapping** is

$$x \mapsto \mathbb{B}z_x = \mathbb{B}\mathbb{W}x$$

Lemma - Equivalent characterization

\bar{x} is a Nash equilibrium iff it is a fixed point of the **game operator** $\mathbb{B}\mathbb{W}$, i.e.

$$\bar{x} = \mathbb{B}\mathbb{W}\bar{x}.$$

Existence and uniqueness

Assumption on cost and strategy sets

- $J(x, z)$ is C^1 and strongly convex in x uniformly in z (constant μ_J)
 $\nabla_x J(x, z)$ is Lipschitz in z uniformly in x (constant ℓ_J)
- $X(s)$ convex and closed $\forall s \in [0, 1]$, $\exists \mathcal{X}$ compact s.t. $X(s) \subseteq \mathcal{X}, \forall s$.

Proof idea: prove that $\mathbb{B}\mathbb{W}$ is a contraction

1. prove that \mathbb{B} is Lipschitz

$$\|\mathbb{B}z_1 - \mathbb{B}z_2\|_{L^2} \leq \frac{\ell_J}{\mu_J} \|z_1 - z_2\|_{L^2}$$

2. combining with \mathbb{W} we get

$$\begin{aligned} \|\mathbb{B}\mathbb{W}x_1 - \mathbb{B}\mathbb{W}x_2\|_{L^2} &\leq \frac{\ell_J}{\mu_J} \|\mathbb{W}x_1 - \mathbb{W}x_2\|_{L^2} = \frac{\ell_J}{\mu_J} \|\mathbb{W}(x_1 - x_2)\|_{L^2} \\ &\leq \frac{\ell_J}{\mu_J} \|\mathbb{W}\| \|x_1 - x_2\|_{L^2} = \frac{\ell_J}{\mu_J} \lambda_{\max}(\mathbb{W}) \|x_1 - x_2\|_{L^2} \end{aligned}$$

3. apply Banach fixed point theorem

Theorem

$$\frac{\ell_J}{\mu_J} \lambda_{\max}(\mathbb{W}) < 1 \quad \Rightarrow \quad \text{existence and uniqueness}$$

Linear quadratic graphon games

$$J(x^i, z^i) = \frac{1}{2}(x^i)^2 - x^i[Kz^i + a]$$

- a Nash equilibrium exists and is unique if

$$\frac{\ell_J}{\mu_J} \lambda_{\max}(\mathbb{W}) < 1 \quad \Leftrightarrow \quad K < \frac{1}{\lambda_{\max}(\mathbb{W})}$$

→ compare with: [Ballester et al., 2006], [Jackson and Zenou, 2014]

- for game of strategic complements ($K > 0$) equilibrium is proportional to **Bonacich centrality**

$$\bar{x}(s) = a((\mathbb{I} - K\mathbb{W})^{-1} \mathbf{1}_{[0,1]})(s)$$

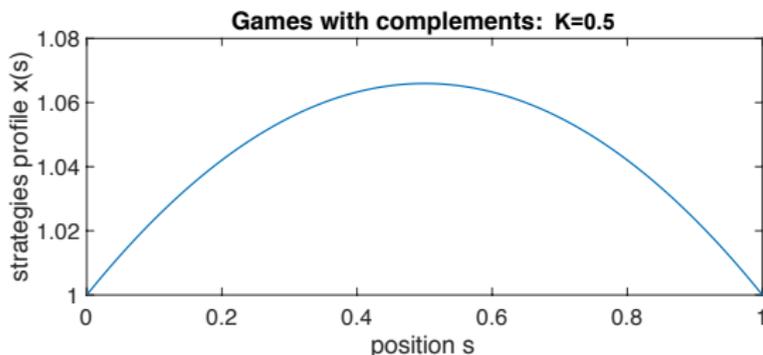
→ centrality measures for graphons:

[Avella-Medina, Parise, Schaub, Segarra. 2017]

Example - cont'd

$$J(x^i, z^i) = \frac{1}{2}(x^i)^2 - x^i[Kz^i + a]$$

- Use minmax graphon and recall $\lambda_{\max}(\mathbb{W}) = \frac{1}{\pi^2}$
- Set $K = 0.5$ (for uniqueness).



Comparative statics

How does the equilibrium change if the graphon changes from \mathbb{W} to $\tilde{\mathbb{W}}$?

Theorem

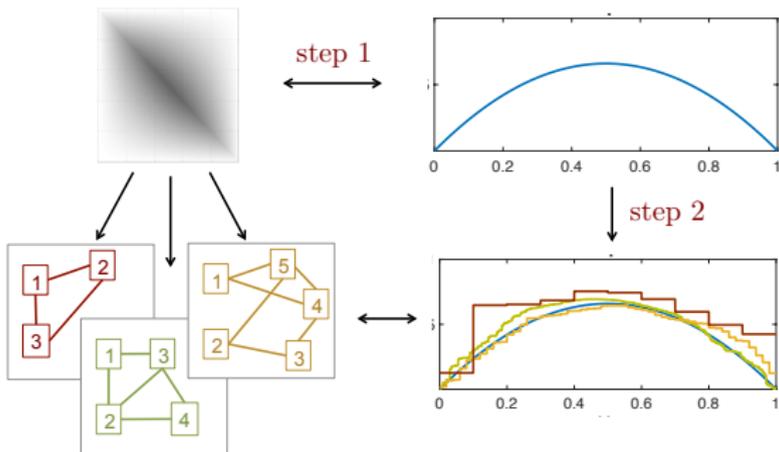
Let $x_{\max} := \max_{x \in \mathcal{X}} \|x\|$. Then under the previous assumptions

$$\|\bar{x} - \tilde{x}\|_{L^2} \leq \frac{\ell_J / \mu_J x_{\max}}{1 - \ell_J / \mu_J \lambda_{\max}(\mathbb{W})} \|\mathbb{W} - \tilde{\mathbb{W}}\|$$

Proof idea:

$$\begin{aligned} \|\bar{x} - \tilde{x}\|_{L^2} &= \|\mathbb{B}\mathbb{W}\bar{x} - \mathbb{B}\tilde{\mathbb{W}}\tilde{x}\|_{L^2} \leq \frac{\ell_J}{\mu_J} \|\mathbb{W}\bar{x} - \tilde{\mathbb{W}}\tilde{x}\|_{L^2} \\ &\leq \frac{\ell_J}{\mu_J} \|\mathbb{W}\bar{x} - \mathbb{W}\tilde{x}\|_{L^2} + \frac{\ell_J}{\mu_J} \|\mathbb{W}\tilde{x} - \tilde{\mathbb{W}}\tilde{x}\|_{L^2} \\ &\leq \frac{\ell_J}{\mu_J} \|\mathbb{W}\| \|\bar{x} - \tilde{x}\|_{L^2} + \frac{\ell_J}{\mu_J} \|\mathbb{W} - \tilde{\mathbb{W}}\| \|\tilde{x}\|_{L^2} \end{aligned}$$

Step 2: finite population



Step 2: Relation sample network and graphon game

Theorem: Nash equilibrium distance

Suppose that W is **Lipschitz continuous** and fix any tolerance $\delta \ll 1$.

With probability at least $1 - 2\delta$

$$\|\bar{x}^{[M]} - \bar{x}\|_{L^2} \leq K \sqrt{\frac{\log(N/\delta)}{N}}$$

Proof idea:

- map any finite network game to a graphon game with



piece-wise constant
graphon $W^{[M]}$

- relate equilibria distance to graphon operator distance:

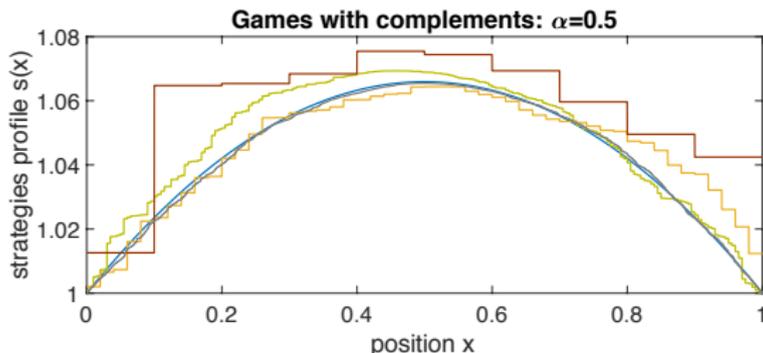
$$\|\bar{x}^{[M]} - \bar{x}\|_{L^2} \leq \tilde{K}_1 \left\| \mathbb{W}^{[M]} - \mathbb{W} \right\|$$

- bound the graphon operator distance (improvement on [Lovász, 2012]):

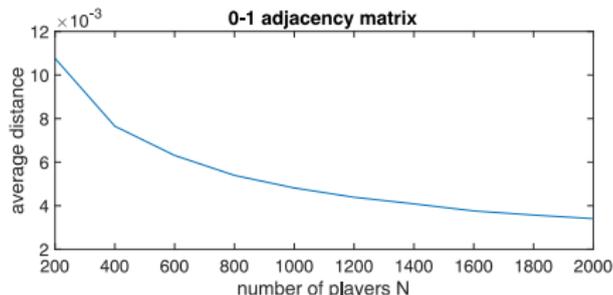
$$\left\| \mathbb{W}^{[M]} - \mathbb{W} \right\| \leq \tilde{K}_2 \sqrt{\frac{\log(N/\delta)}{N}}$$

Example - cont'd

Use minmax graphon and recall $\lambda_{\max}(\mathbb{W}) = \frac{1}{\pi^2}$. Set $\alpha = 0.5$ (for uniqueness).



- Plot the equilibrium in sampled network games for $N = 10, 50, 200, 2000$
- Plot **expected distance** over 100 realizations



Step 3:
Interventions

Welfare maximization in LQ network games

$$J(x^i, z^i) = \frac{1}{2}(x^i)^2 - x^i[Kz^i + a^i], \quad K > 0$$

This could model for example peer pressure in education: [Calvó-Armengol, Patacchini, Zenou \(2009\)](#)

- x^i = student effort
- K = level of peer pressure
- a^i = effort in isolation

Welfare maximization in LQ network games

$$J(x^i, z^i | \beta^i) = \frac{1}{2}(x^i)^2 - x^i[Kz^i + a^i + \beta^i]$$

Per-capita welfare maximization problem - Galeotti et al., (2017):

$$\begin{aligned} \max_{\beta \in \mathbb{R}^N} \quad & T_{\beta}^{[M]} := -\frac{1}{N} \sum_{i=1}^N J(\bar{x}^i, \bar{z}^i | \beta^i) \\ \text{s.t.} \quad & \sum_{i=1}^N (\beta^i)^2 \leq C^{[M]}, \end{aligned}$$

Network heuristic

$$\beta_{\text{nh}}^{[M]} := \sqrt{C^{[M]}} v_1^{[M]}$$

where $v_1^{[M]}$ is the **dominant eigenvector** of $G^{[M]}$

Graphon heuristic

$$[\beta_{\text{gh}}^{[M]}]_i := \kappa^{[M]} \cdot \psi_1(s_i),$$

where ψ_1 is the **dominant eigenfunction** of W

Performance of the graphon heuristic

Theorem

If further $\lambda_1(\mathbb{W}) > \lambda_2(\mathbb{W})$ and $C^{[M]} = \mathcal{O}(N)$, with probability $1 - 2\delta$

$$|T_{nh}^{[M]} - T_{gh}^{[M]}| = \mathcal{O}\left(\sqrt{\frac{\log(N/\delta)}{N}}\right).$$

Proof idea:

- i) $T^{[M]} = \frac{1}{2N} \|\bar{x}^{[M]}\|^2$ and ii) $\bar{x}^{[M]} = [I - \alpha \frac{G^{[M]}}{N}]^{-1}(a + \beta)$

$$\begin{aligned} |T_{nh}^{[M]} - T_{gh}^{[M]}| &\leq \frac{\sqrt{C^{[M]}} + a\sqrt{N}}{N} \frac{1}{(1 - \eta K \lambda_1(\mathbb{W}))^2} \|\beta_{nh}^{[M]} - \beta_{gh}^{[M]}\| \\ &\approx \frac{\sqrt{C^{[M]}} + a\sqrt{N}}{N} \frac{\sqrt{C^{[M]}}}{(1 - \eta K \lambda_1(\mathbb{W}))^2} \|\varphi_1^{[M]} - \varphi_1\|_{L^2} \end{aligned}$$

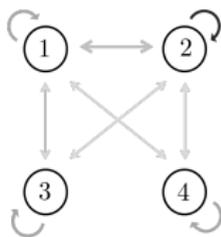
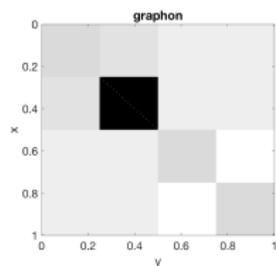
- By Davis-Kahan theorem

$$\left\| \underbrace{\varphi_1^{[M]}}_{\text{rel. to } \mathbb{W}^{[M]}} - \underbrace{\varphi_1}_{\text{rel. to } \mathbb{W}} \right\|_{L^2} \leq \frac{2\sqrt{2} \left\| \mathbb{W}^{[M]} - \mathbb{W} \right\|}{\lambda_1(\mathbb{W}) - \lambda_2(\mathbb{W})} = \mathcal{O}\left(\sqrt{\frac{\log(N/\delta)}{N}}\right)$$

The community model

SBM model

- generalize to K communities
- each agent belongs to community k with probability w_k
- agents in community l, k connect with probability $q_{l,k}$

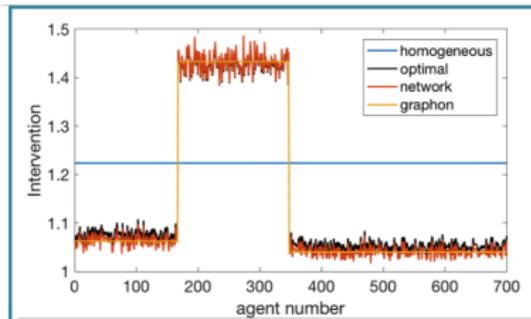
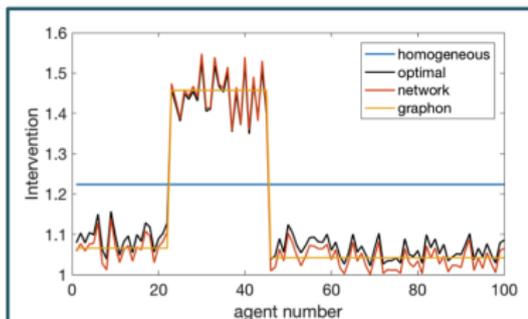
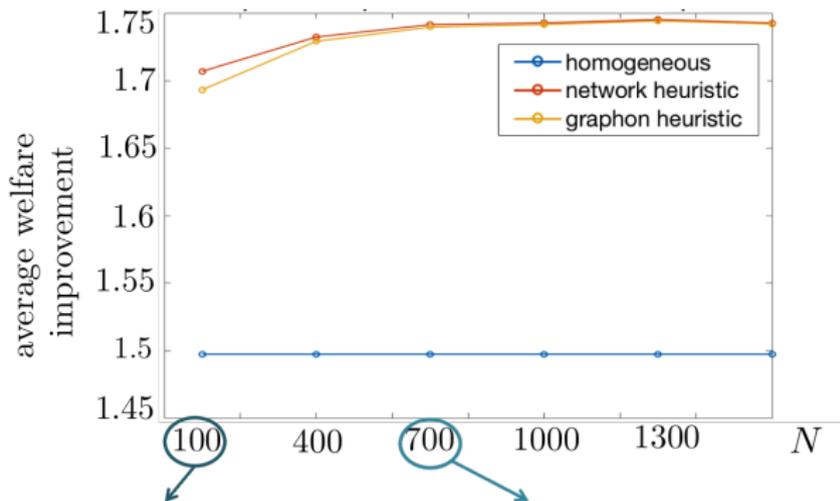


(e.g. [Currarini et al. \(2009\)](#) community= students of different race)

How to compute the dominant eigenfunction?

- Let $D := \text{diag}([w_k]) \in \mathbb{R}^{4 \times 4}$
- Let $Q := [q_{l,k}] \in \mathbb{R}^{4 \times 4}$
- Let v_1 dominant eigenvector of $QD \in \mathbb{R}^{4 \times 4}$
- Then $\psi_1(s)$ is piece-wise constant with values given by v_1

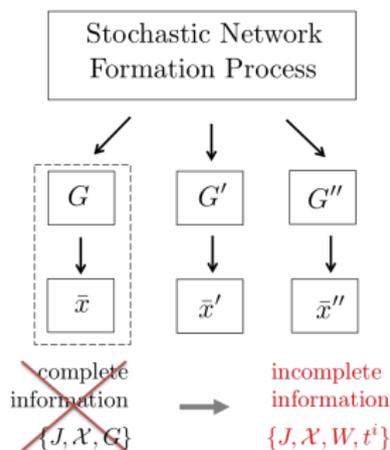
The community model - cont'd



The graphon heuristic is much simpler to implement

Step 4:
Incomplete information

Incomplete information in sampled network games



An **incomplete information sampled network game** $\mathcal{G}^{in}(x, J, W)$ is a game

- with a random number N of agents
- with types $\{t^i\}_{i=1}^N$ sampled i.i.d from $\mathcal{U}[0, 1]$
- interacting according to a network $G^{[M]}$ sampled from the graphon W
- each agent i has information about: W, t^i, \mathcal{X} and J
- while is **uninformed about $G^{[M]}$ and the other agents types t^{-i}**

Symmetric Bayesian Nash equilibrium

- Suppose agent of type s play $b(s)$ (symmetric case)
- The expected cost of an agent of type $t^i = s$ playing $x(s) \in X(s)$ is

$$J_{\text{exp}}(x(s) | b) = \mathbb{E}_{N, t^{-i}, \text{links}} \left[J \left(x(s), \frac{1}{N-1} \sum_{j \neq i} [G^{[M]}]_{ij} b(t^j) \right) \right]$$

Symmetric Bayesian Nash equilibrium

$b(s) \in X(s)$ is a symmetric ε -Bayesian Nash equilibrium if for all $s \in [0, 1]$

$$J_{\text{exp}}(b(s) | b) \leq J_{\text{exp}}(\tilde{x} | b) + \varepsilon \text{ for all } \tilde{x} \in X(s).$$

Symmetric Bayesian Nash eq. are strictly related to graphon Nash eq.

Linear quadratic games

Theorem

\bar{x} is a Nash equilibrium of $\mathcal{G}(X, J, W)$ iff it is a symmetric Bayesian Nash equilibrium of $\mathcal{G}^{in}(X, J, W)$.

Proof idea:

- \bar{x} Graphon equilibrium iff $J(\bar{x}(s), \bar{z}(s)) \leq J(\tilde{x}, \bar{z}(s)), \forall \tilde{x}, s$

$$\bar{z}(s) = \int_0^1 W(s, t) \bar{x}(t) dt$$

- Fix $b = \bar{x}$, by linearity in aggregate: $J_{\text{exp}}(x(s) | \bar{x}) = J(x(s), z_{\text{exp}}(s))$ where

$$z_{\text{exp}}(s) := \mathbb{E}_{N, t^{-i}, \text{links}} \left[\frac{1}{N-1} \sum_j [G^{[M]}]_{ij} \bar{x}(t^j) \right]$$

- \bar{x} Bayesian equilibrium iff $J(\bar{x}(s), z_{\text{exp}}(s)) \leq J(\tilde{x}, z_{\text{exp}}(s)), \forall \tilde{x}, s$.

- Conclusion follows from $z_{\text{exp}}(s) = \bar{z}(s)$

$$\begin{aligned} z_{\text{exp}}(s) &= \mathbb{E}_N \mathbb{E}_{t^{-i} | N} \mathbb{E}_{\text{links} | t^{-i}, N} \left[\frac{1}{N-1} \sum_{j \neq i} [G^{[M]}]_{ij} \bar{x}(t^j) \right] \\ &= \mathbb{E}_N \mathbb{E}_{t^{-i} | N} \left[\frac{1}{N-1} \sum_{j \neq i} W(s, t^j) \bar{x}(t^j) \right] = \mathbb{E}_N \frac{1}{N-1} \sum_{j \neq i} \mathbb{E}_{t^j} [W(s, t^j) \bar{x}(t^j)] \\ &= \mathbb{E}_N \frac{1}{N-1} \sum_{j \neq i} \int_0^1 W(s, t) \bar{x}(t) dt = \mathbb{E}_N \frac{1}{N-1} \sum_{j \neq i} \bar{z}(s) = \mathbb{E}_N \bar{z}(s) = \bar{z}(s) \end{aligned}$$

Generalization to Lipschitz cost

Theorem

Further suppose that

- $J(x, z)$ is Lipschitz continuous in z uniformly over x
- agents know that $N \geq N_{\min}$

The Nash equilibrium of $\mathcal{G}(X, J, W)$ is a symmetric ε -Bayesian Nash equilibrium with

$$\varepsilon = \mathcal{O} \left(\sqrt{\frac{\log(N_{\min})}{N_{\min}}} \right).$$

Proof idea:

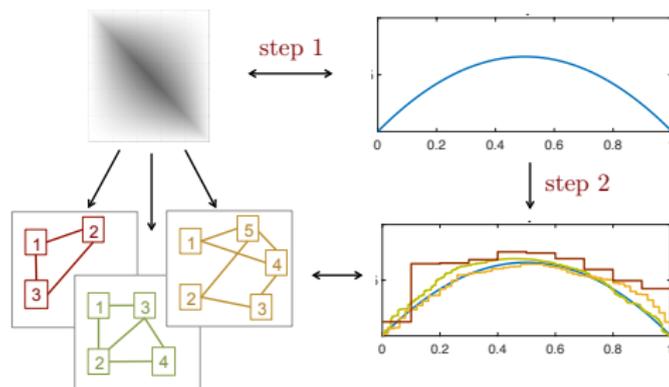
- For general cost

$$\begin{aligned} J_{\text{exp}}(x(s) \mid \bar{x}) &= \mathbb{E}_{N, t^{-i}, \text{links}} \left[J \left(x(s), \frac{1}{N-1} \sum_j [G^{[M]}]_{ij} \bar{x}(t^j) \right) \right] \neq J(x(s), z_{\text{exp}}(s)) \\ &= \mathbb{E}_{\zeta_{\bar{x}}(s)} [J(x(s), \zeta_{\bar{x}}(s))] \end{aligned}$$

- Prove that $\zeta_{\bar{x}}(s)$ concentrates around $z_{\text{exp}}(s)$ for N large
- Use Lipschitz condition to show that

$$J_{\text{exp}}(x(s) \mid \bar{x}) \approx J(x(s), z_{\text{exp}}(s)) = J(x(s), \bar{z}(s))$$

Conclusion



Summary

- Define graphon games and study equilibrium properties
- Graphon equilibrium is a good approximation for sampled network games
- Shown how to design robust interventions using graphon model
- Foundation for graphon equilibrium in incomplete information games