



Thursday September 19, 2019 at 14:30 Politecnico di Torino, DISMA, Aula Buzano (third floor)

Richard PATES

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Modular control system design for platooning problems

Prof. Giacomo Como introduces the seminar

Abstract

The modular approach to control system design aims to design control systems for individual "components" in such a way that performance is maintained even as they are interconnected. It offers a simple way to design for performance that provides provable guarantees that hold even in extremely large systems.

In this talk, Dr. Pates will illustrate a modular design method tailored specifically for the problem of organising a set of vehicles into a platoon.

Biography

Richard Pates received the engineering and PhD degrees in 2009 and 2014 respectively, both from the University of Cambridge. His thesis, titled "Scalable design rules for heterogeneous networks", was done under the supervision of Glenn Vinnicombe. Since leaving Cambridge, he have spent 4 years as a postdoc in Lund with Anders Rantzer.